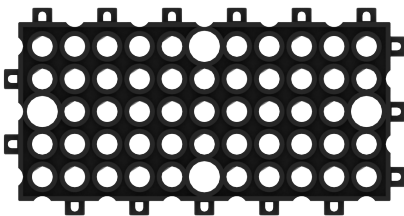


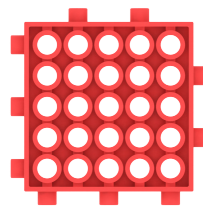
## 51 ROBOT PINTOR



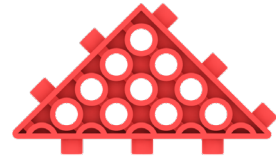
## Piezas



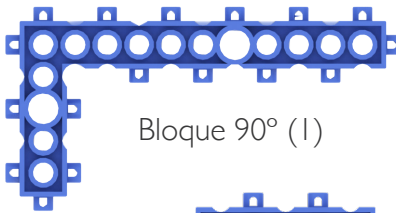
Bloque 5x11 (2)



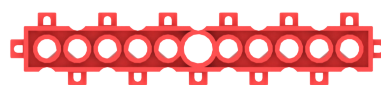
Bloque 5x5 (2)



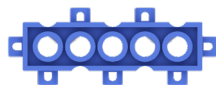
Bloque triangular (4)



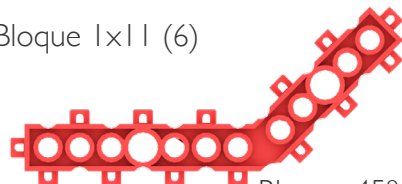
Bloque 90° (1)



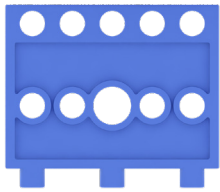
Bloque 1x11 (6)



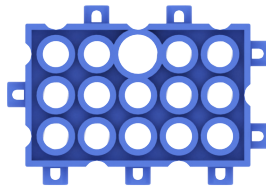
Bloque 1x5 (2)



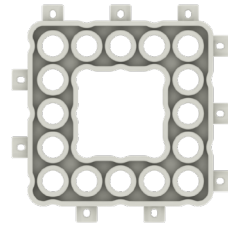
Bloque 45° (6)



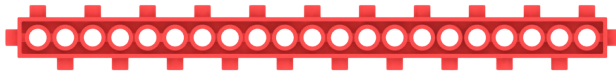
Soporte de motor (2)



Bloque 3x5 (2)



Bloque cuadrado 5x5 (2)



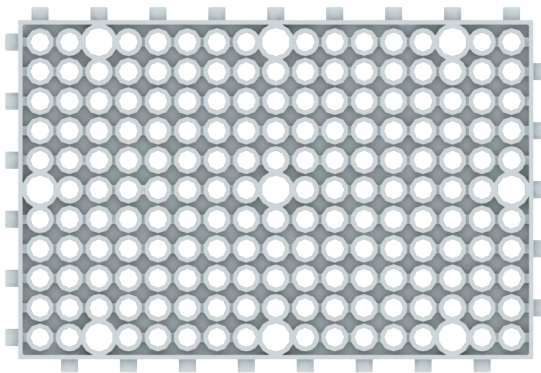
Bloque 1x21 (1)



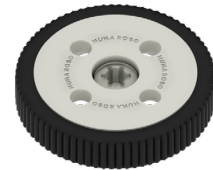
Goma de eje roja (2)



Bloque ojo (2)



Bloque 11x17 (1)



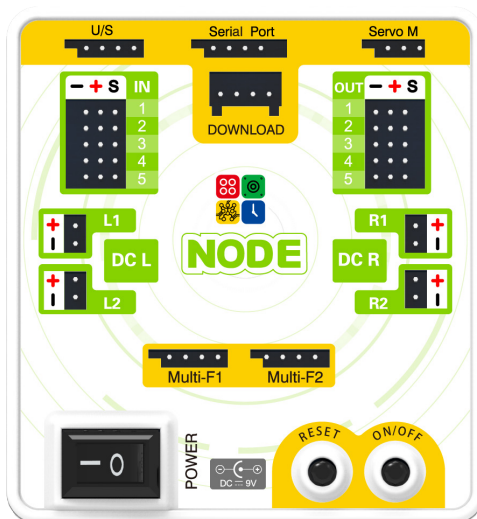
Rueda S (2)



Alargador de cable (1)



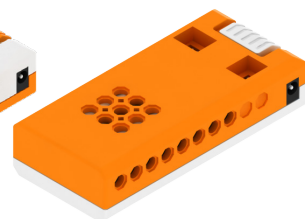
Cable de conexión (3)



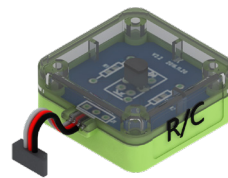
Placa base NODE (1)



Portapilas o portabaterías 1 (1)



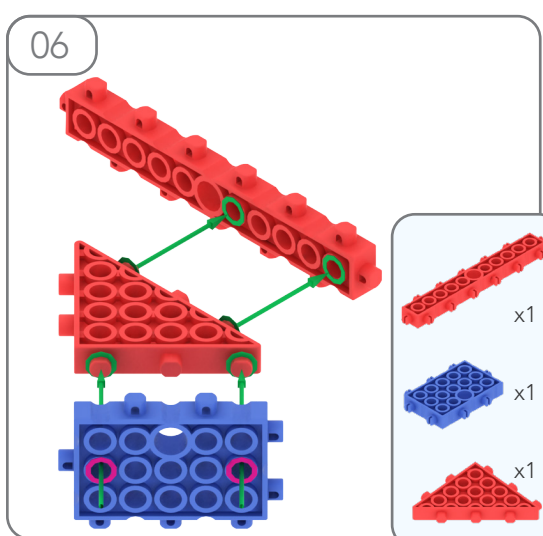
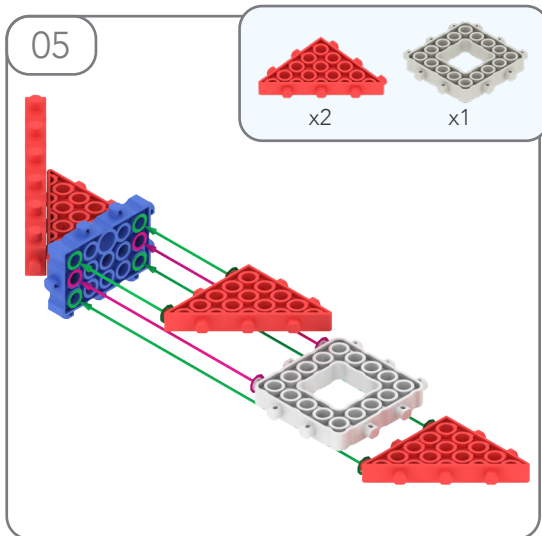
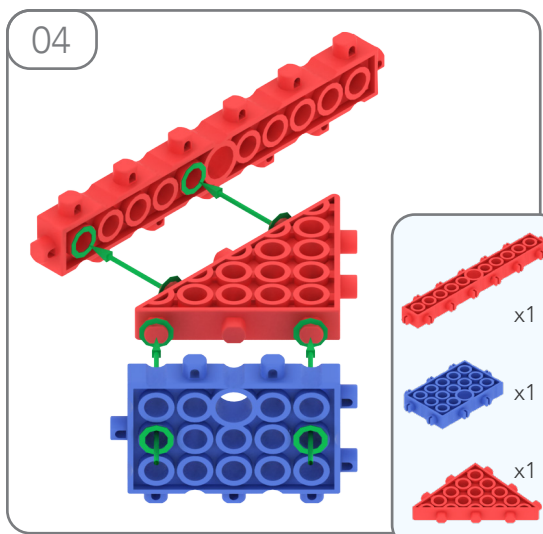
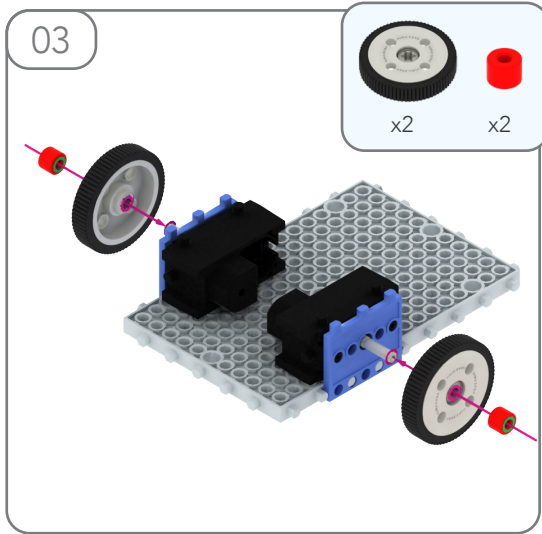
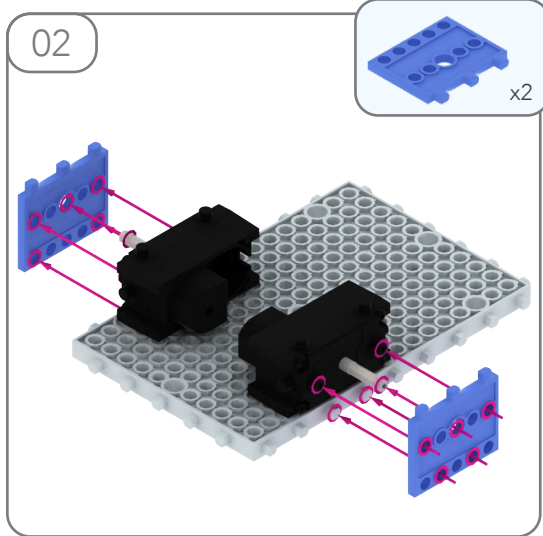
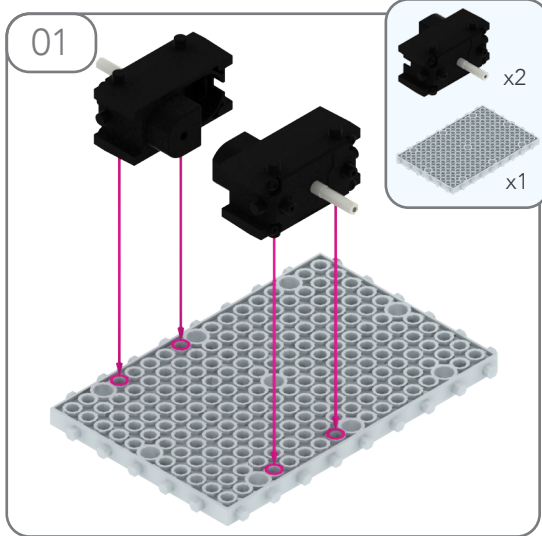
Portapilas o portabaterías 2 (2)



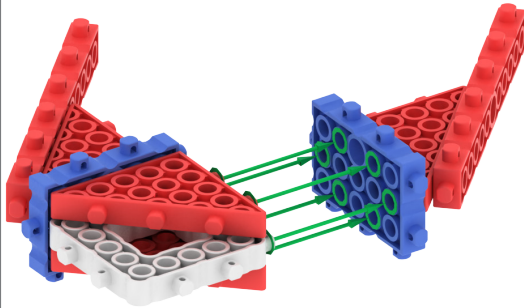
Sensor R/C (1)



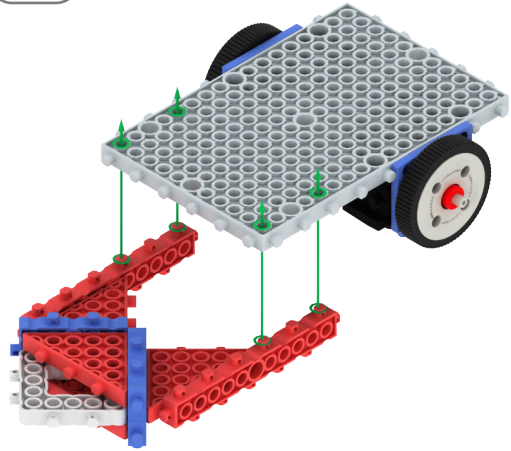
Motor 2 (2)



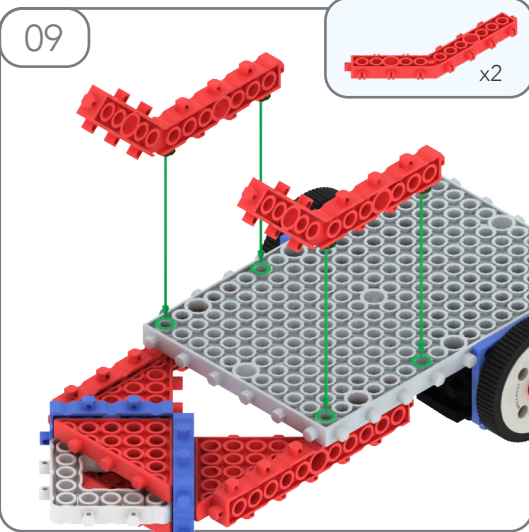
07



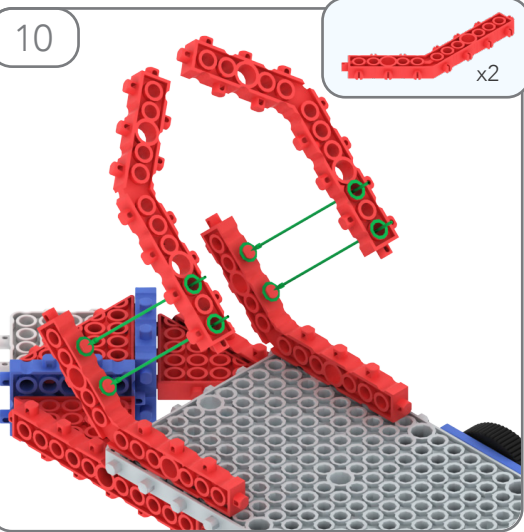
08



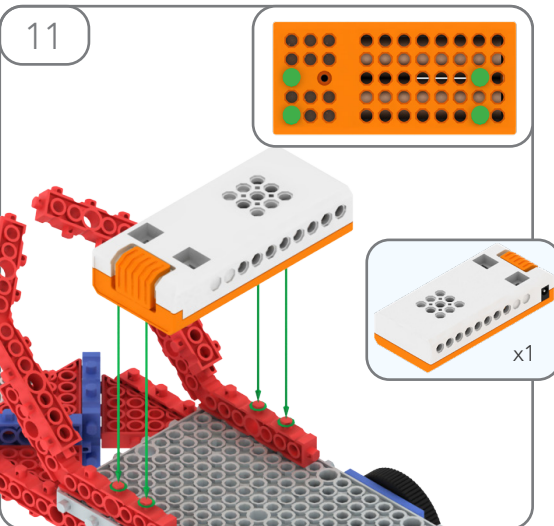
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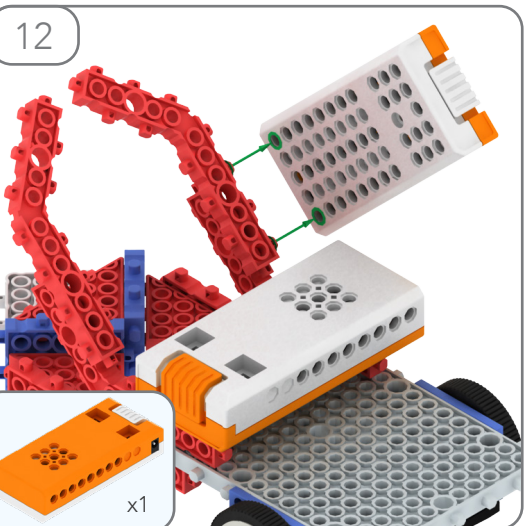
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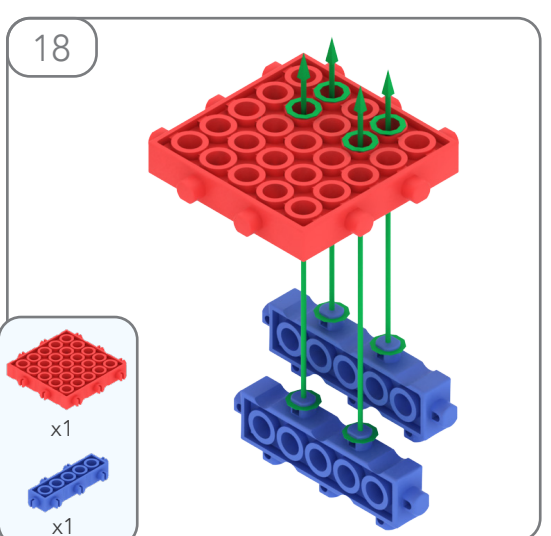
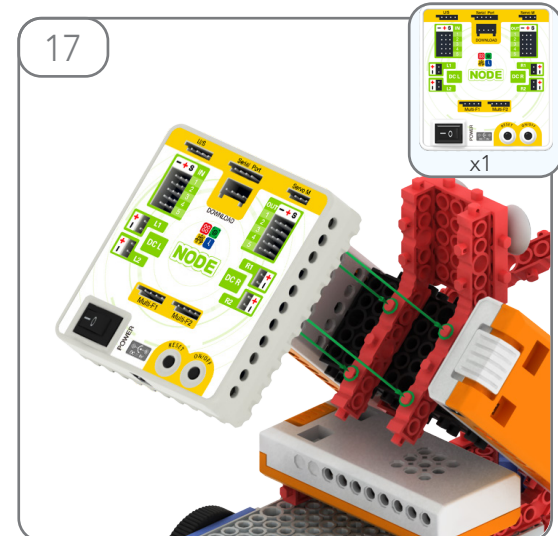
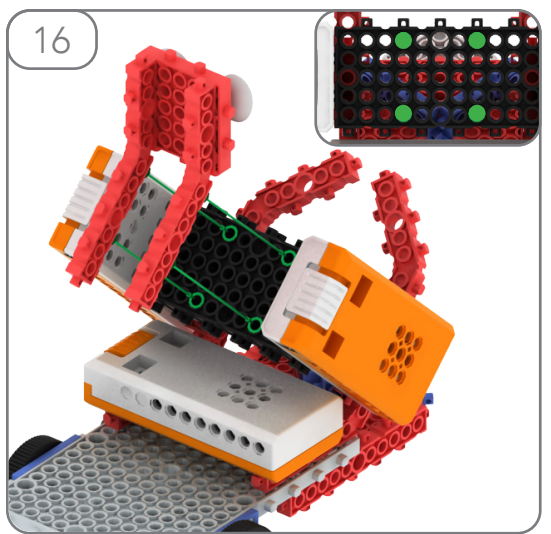
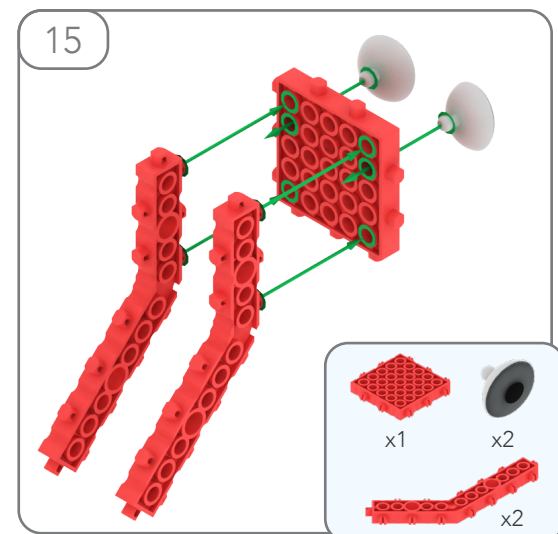
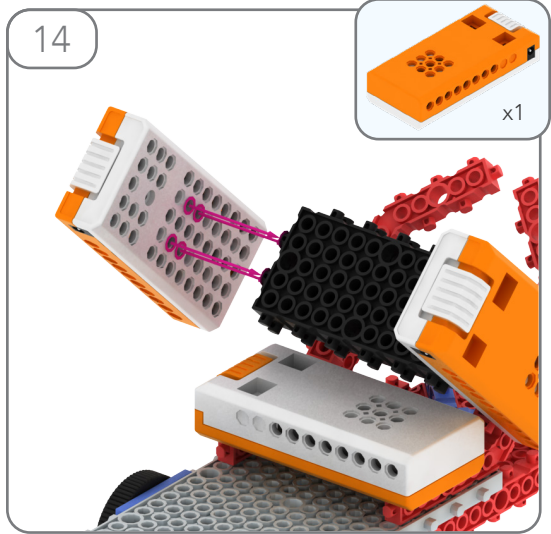
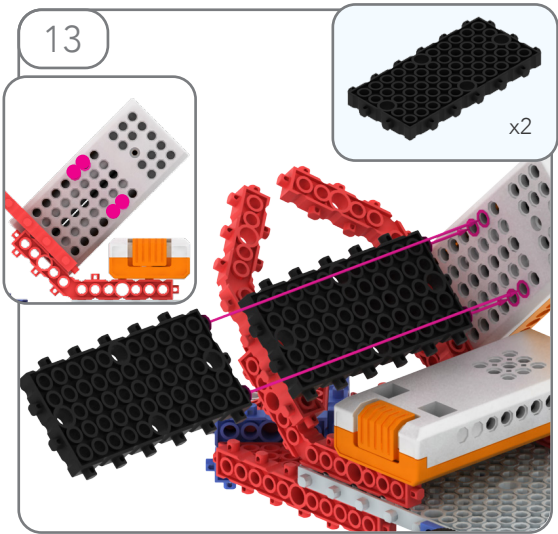


11

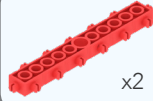
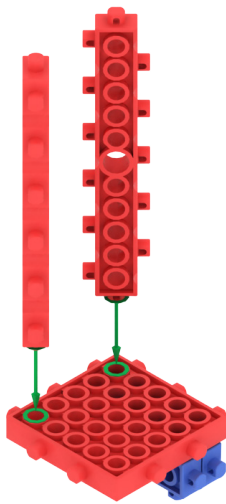


12

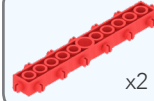
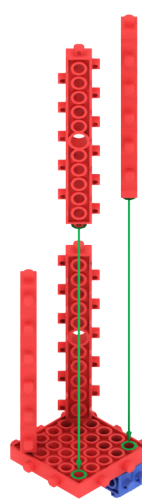




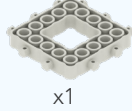
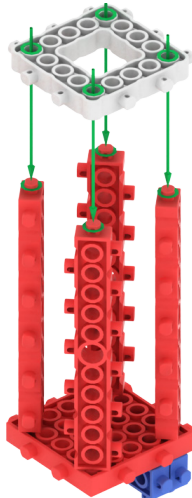
19



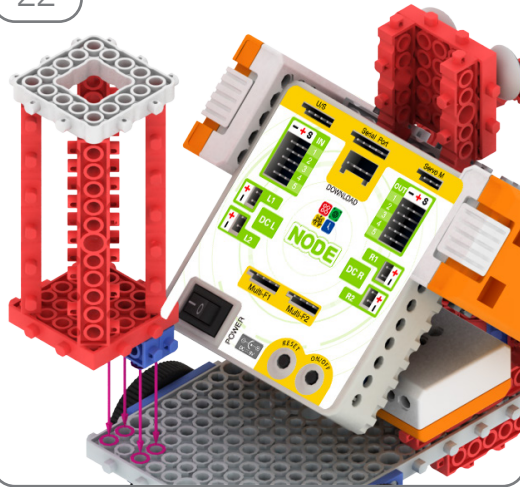
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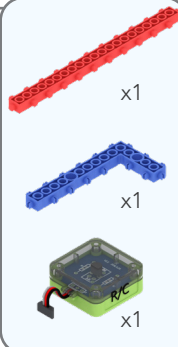
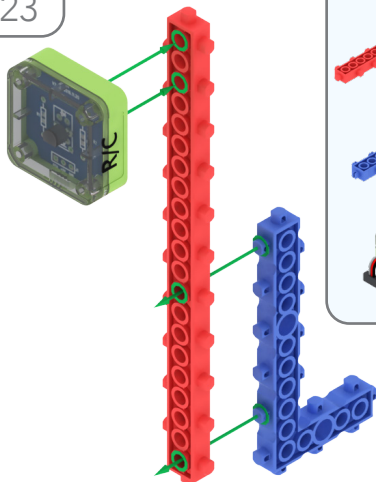
21



22



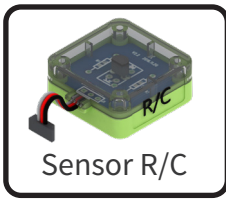
23



OK



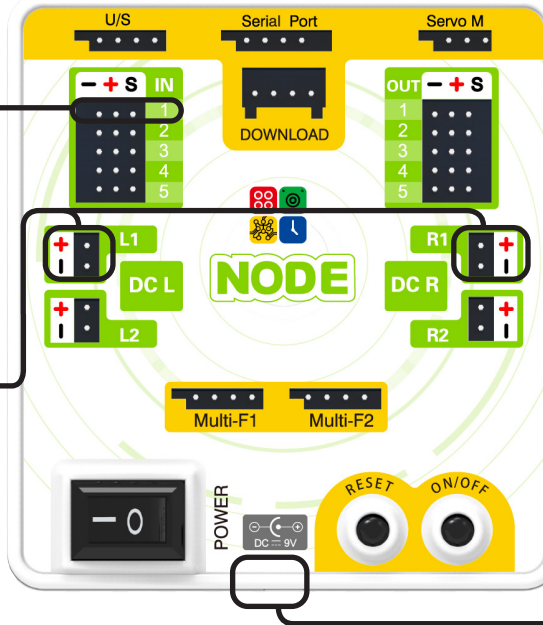
## ¿Cómo hacer la conexión?



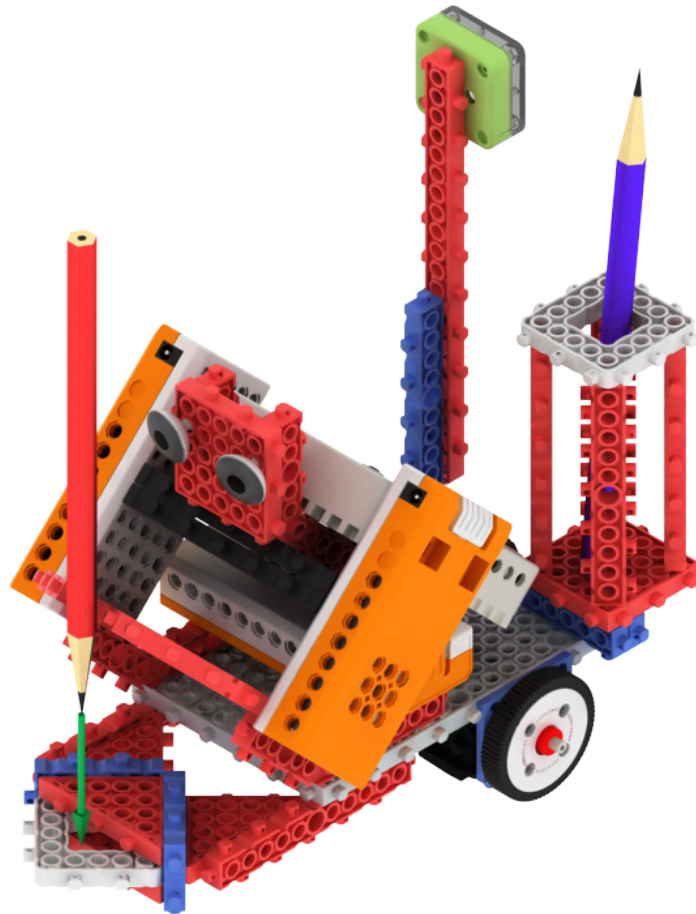
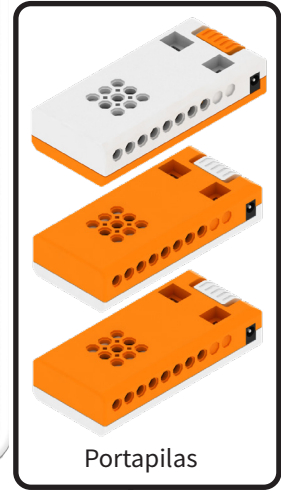
R/C



LEFT1,RIGHT1



ENERGÍA



Practica

