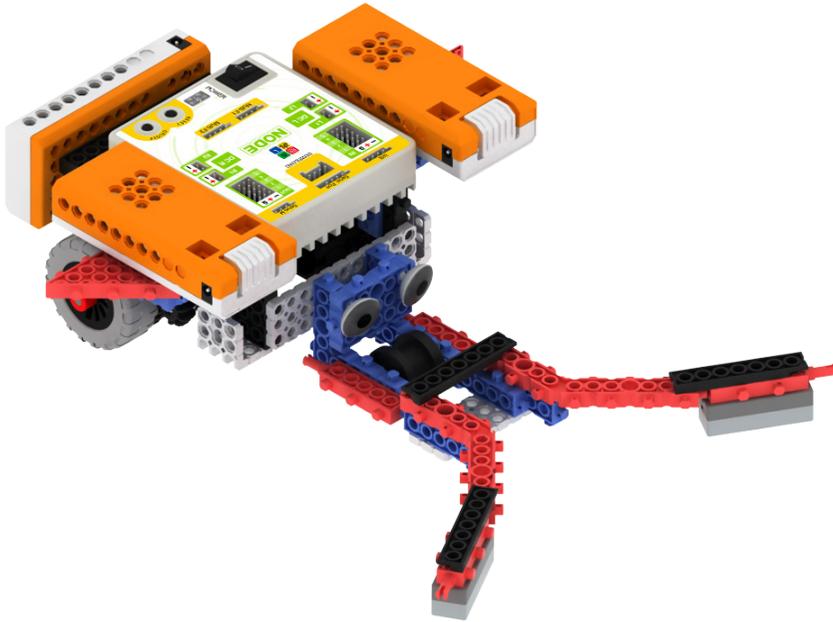
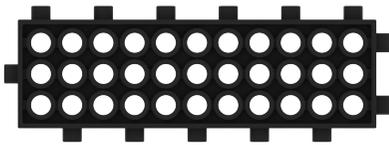


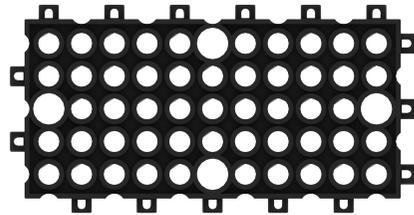
## 49 Hemiptera



## Piezas



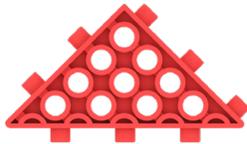
Bloque 3x11 (1)



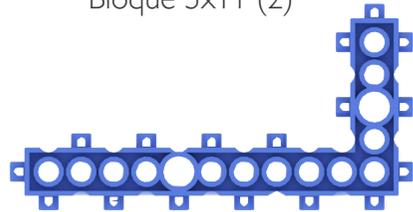
Bloque 5x11 (2)



Adaptador L (6)



Bloque triangular (2)



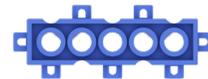
Bloque 90 ° (2)



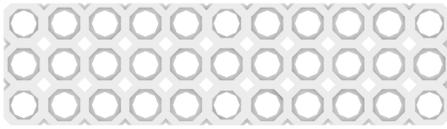
Bloque con eje (4)



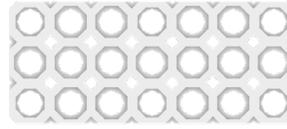
Bloque de unión 2 (3)



Bloque 1x5 (6)



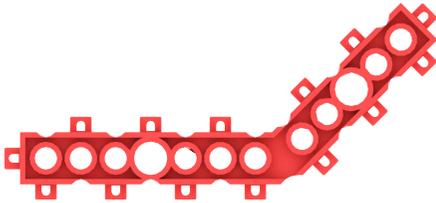
Bloque N 3x11 (2)



Bloque 3x7 N (1)



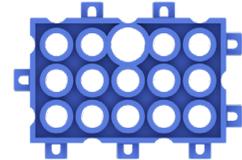
Adaptador L  
3x4 (2)



Bloque 135° (2)



Bloque ojo (2)



Bloque 3x5 (4)



Engranaje S (2)



Engranaje L (2)



Rueda L (2)

**S-shaft**

Eje S (1)

**M-shaft**

Eje M (2)



Arandela (6)



Goma de eje  
roja (4)



Rueda polea (1)



Cable de conexión (3)



Motor 2 (2)



Sensor de infrarrojos (2)



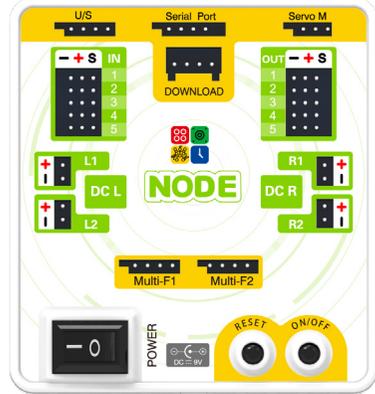
Cable USB (1)



Portapilas o portabaterías 1 (1)



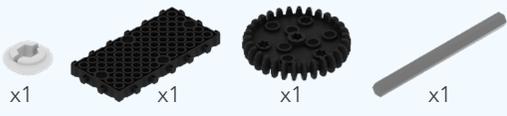
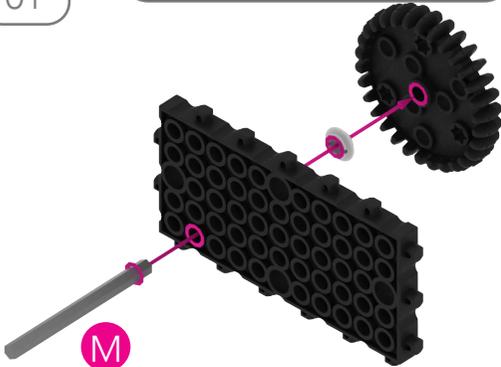
Portapilas o portabaterías 2 (2)



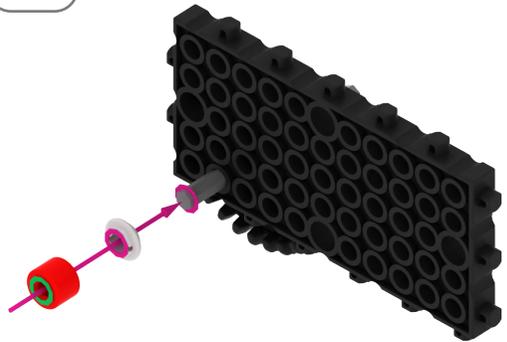
Placa base NODE (1)

01

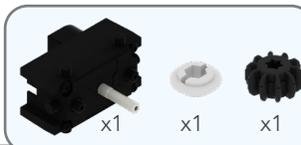
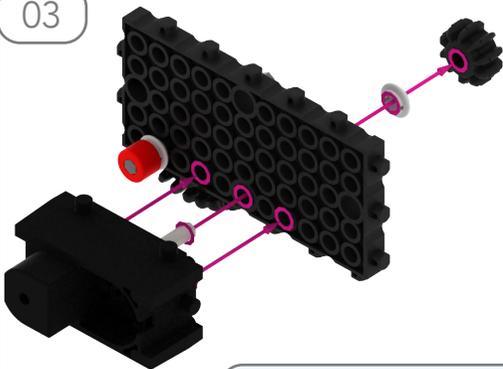
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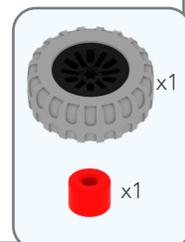
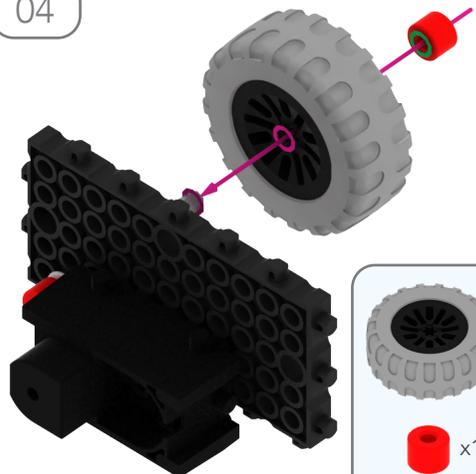
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03

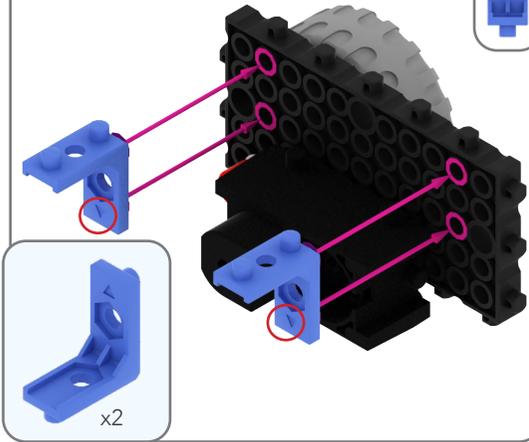


04



05

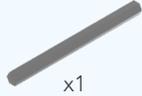
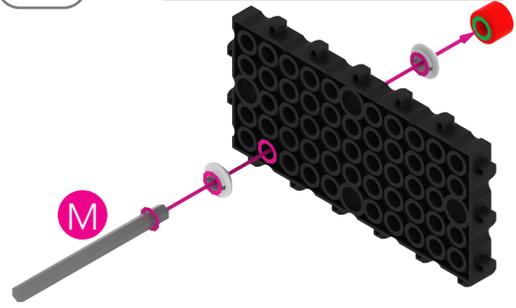
Este triángulo rojo "▲" señala la posición.



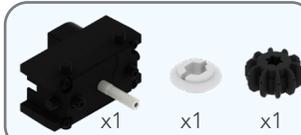
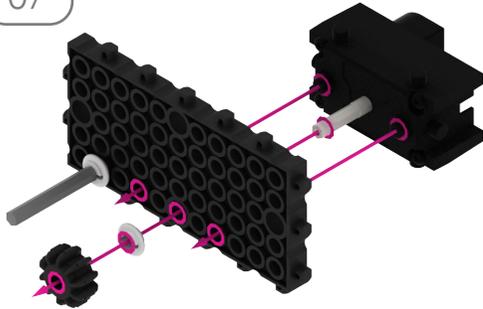
x2

06

1:1

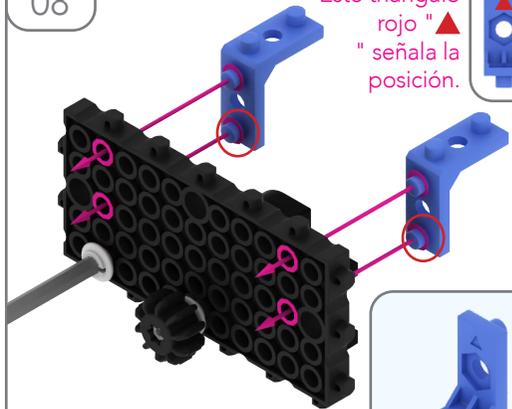


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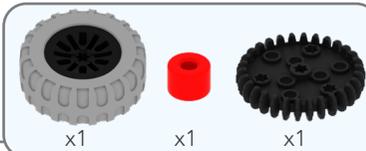
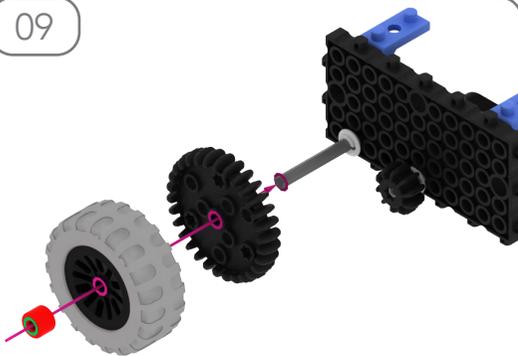


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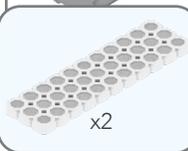
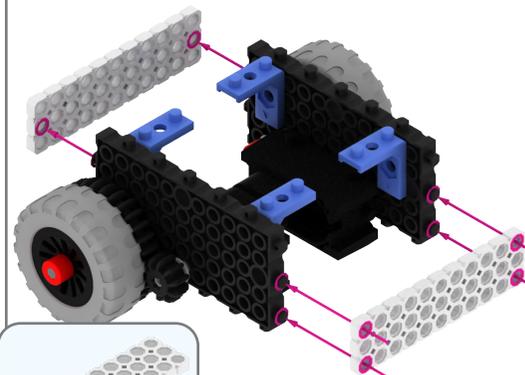
Este triángulo rojo "▲" señala la posición.



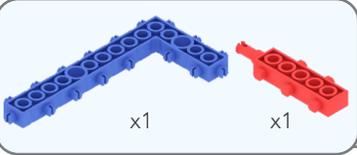
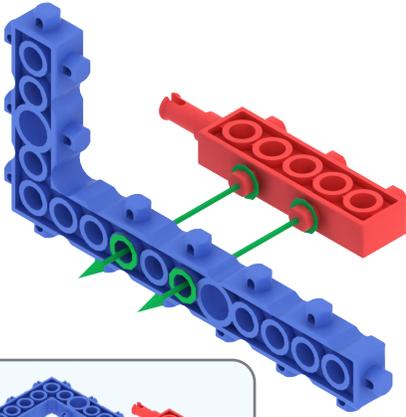
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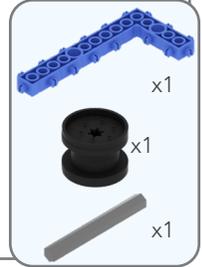
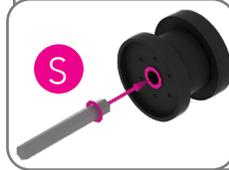
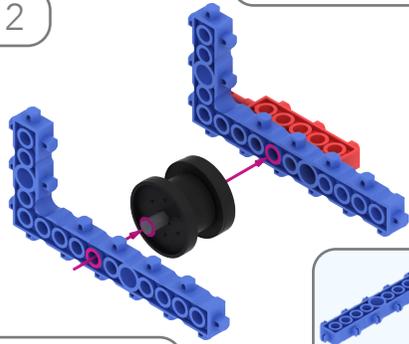


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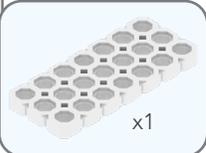
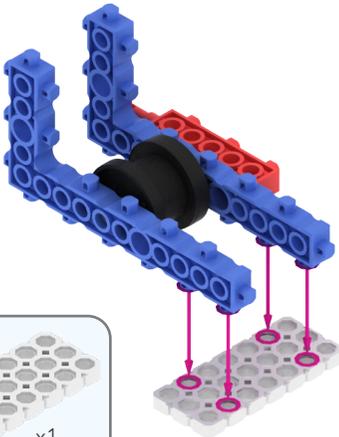


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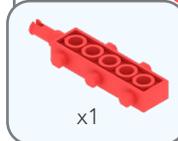
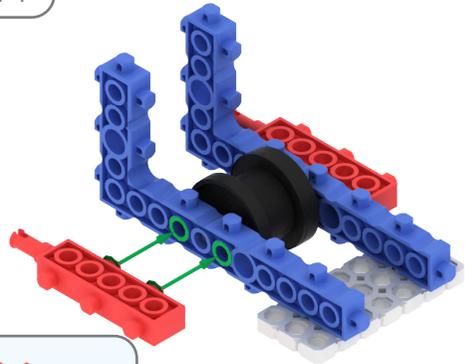
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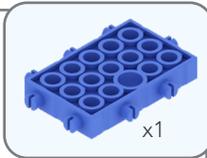
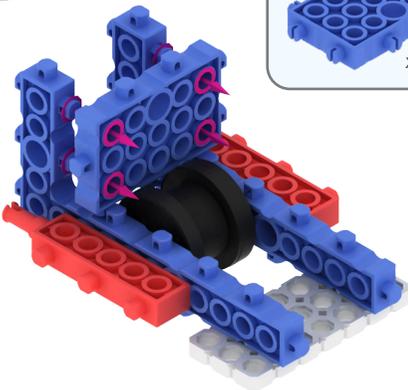
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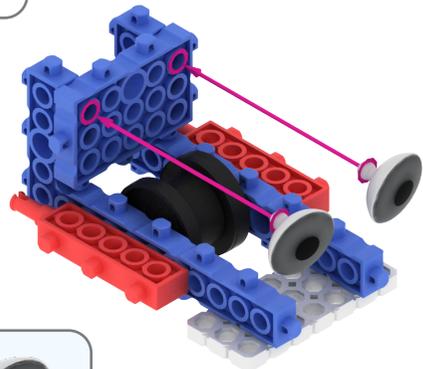
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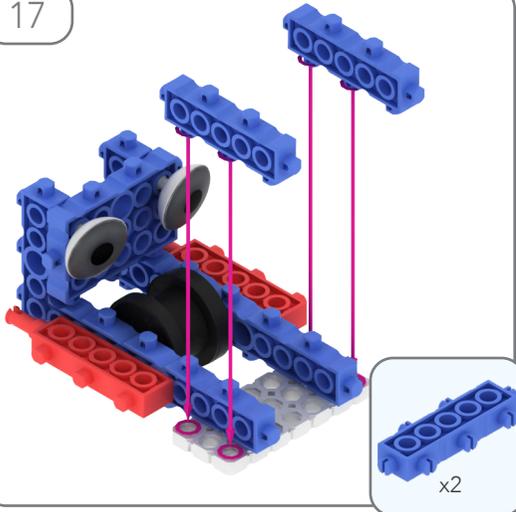
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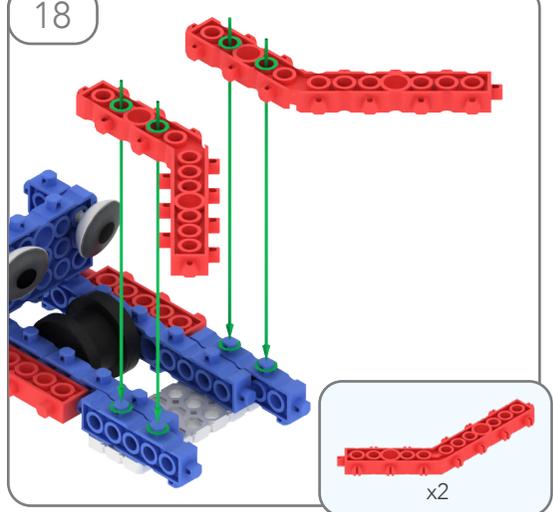
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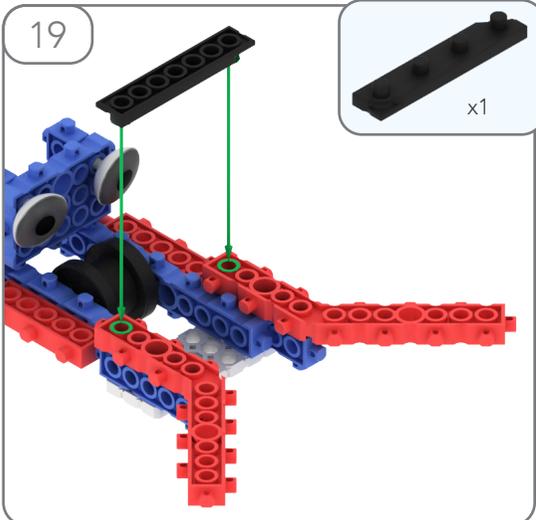
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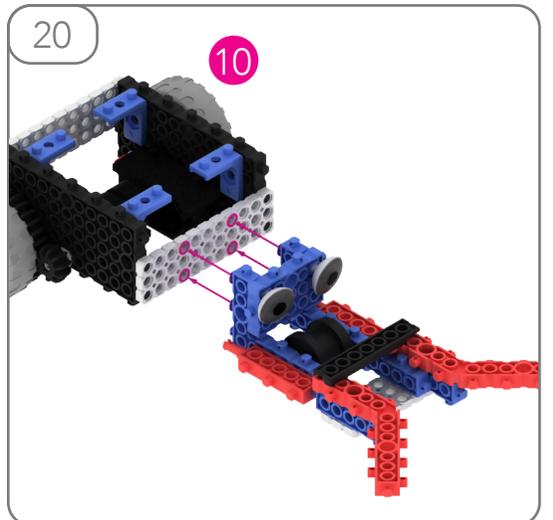
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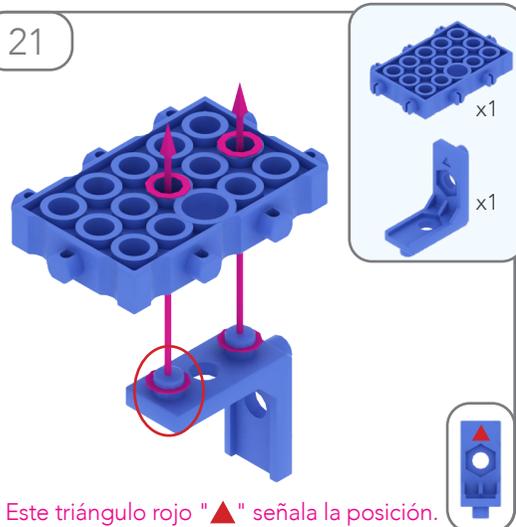
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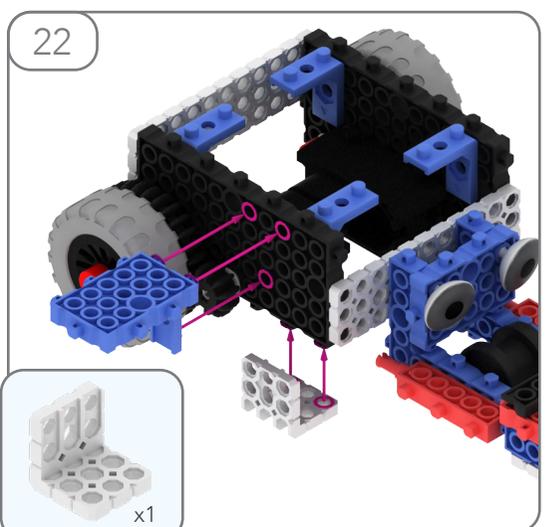
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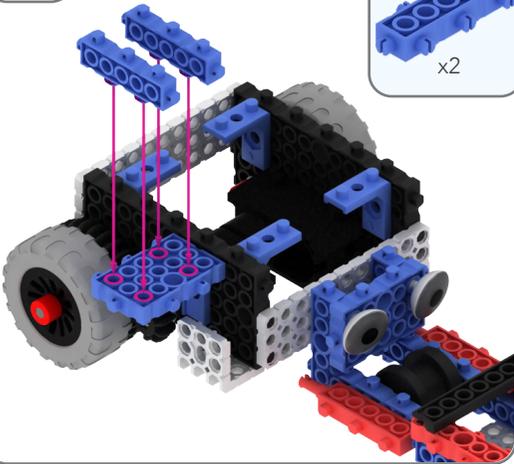
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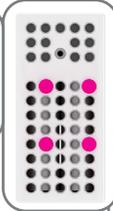
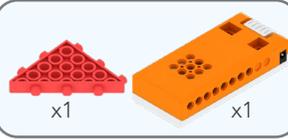
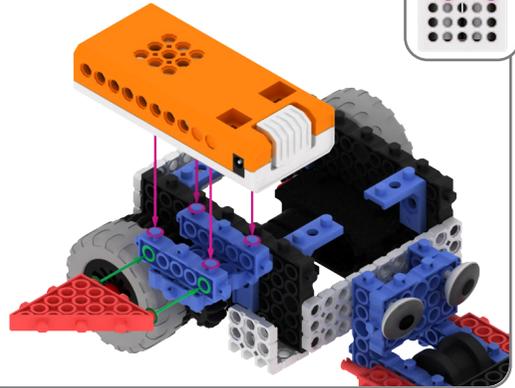
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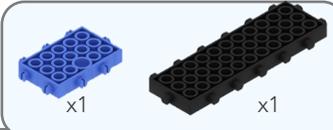
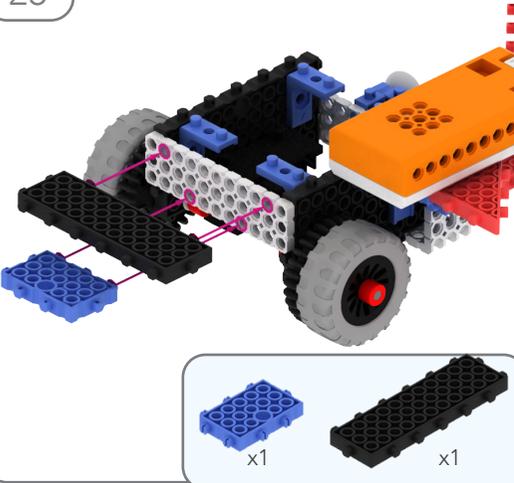
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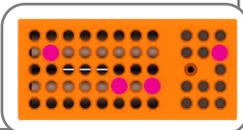
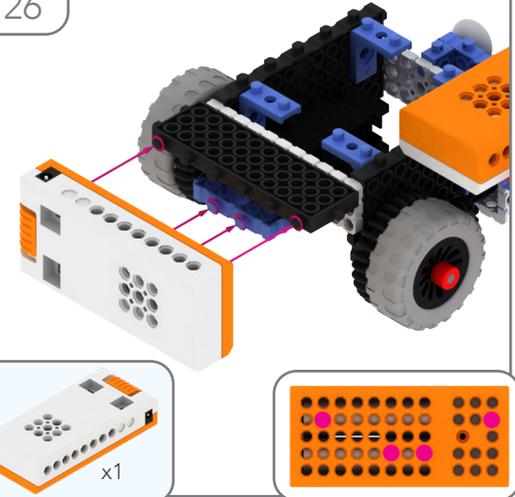
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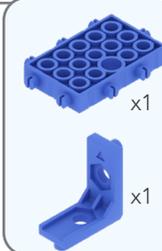
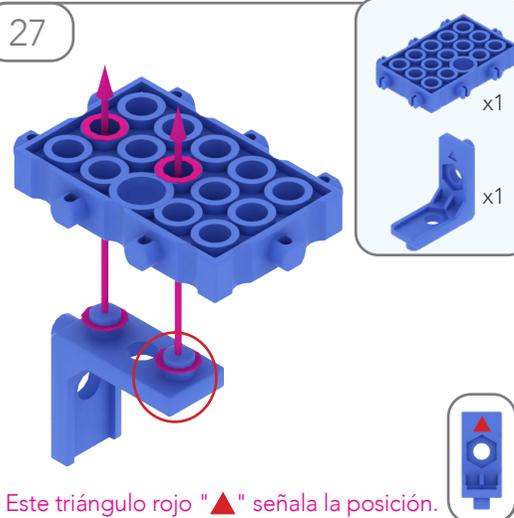
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26

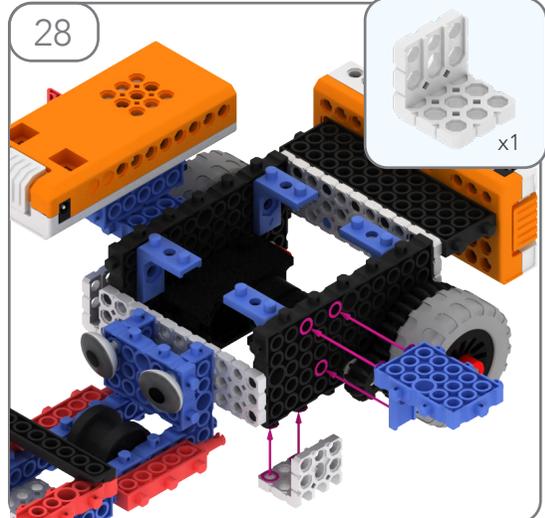


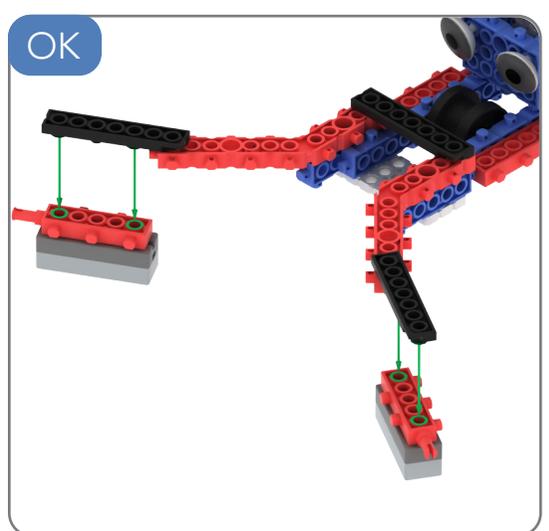
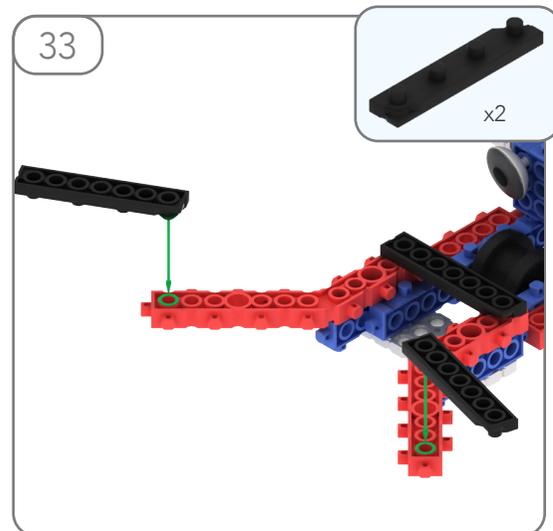
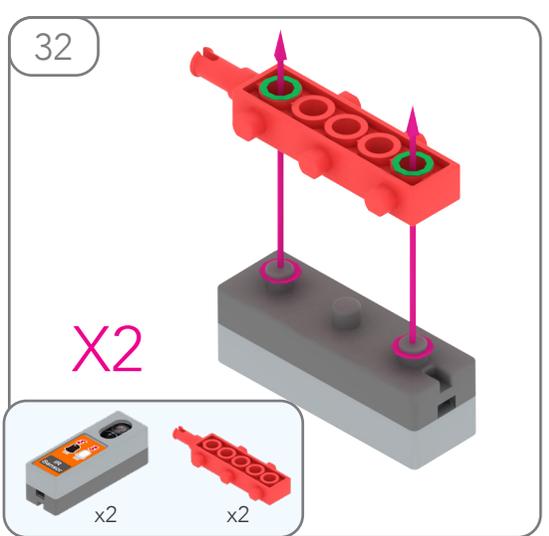
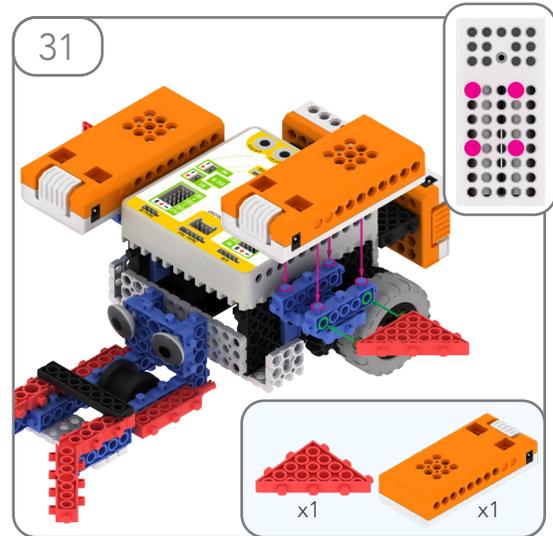
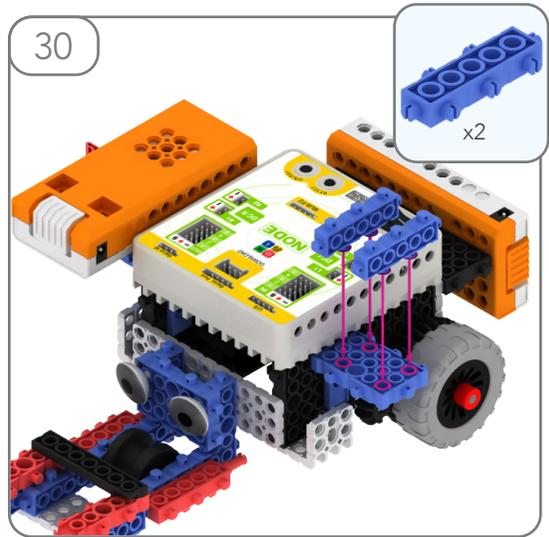
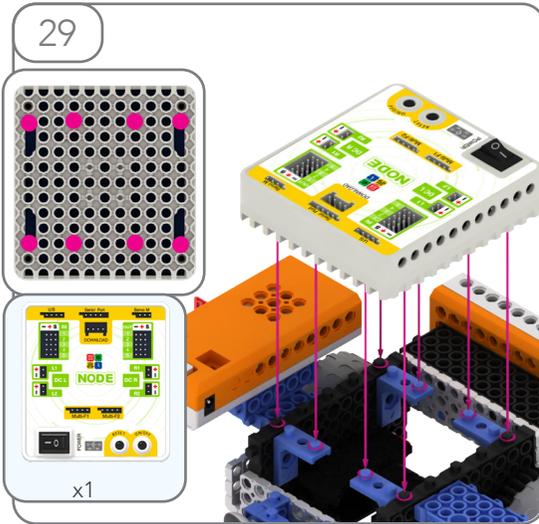
27



Este triángulo rojo "▲" señala la posición.

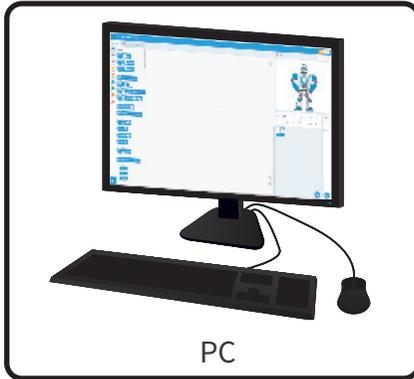
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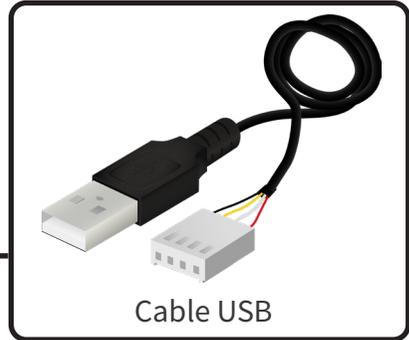


# ¿Cómo hacer la conexión?

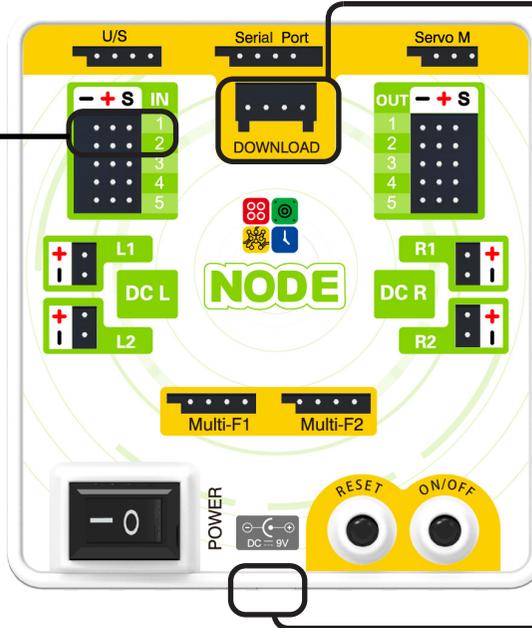
USB



USB/Download



IN1, IN2



POWER

