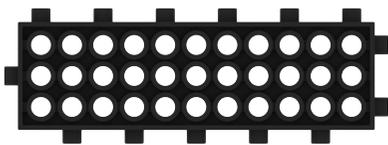


42 Pato



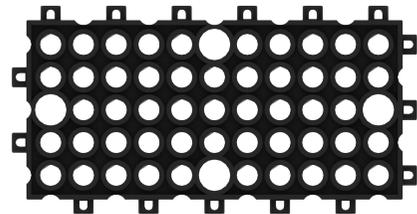
Piezas



Bloque 3x11 (3)



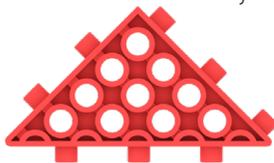
Goma de eje roja (2)



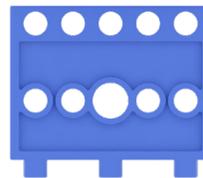
Bloque 5x11 (1)



Adaptador L (5)



Bloque triangular (1)



Soporte de motor (4)



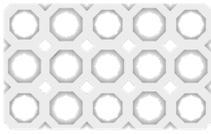
Bloque ojo (2)



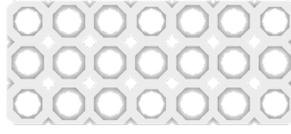
Bloque 1x21 (1)



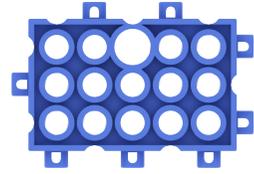
Bloque 1x5 (4)



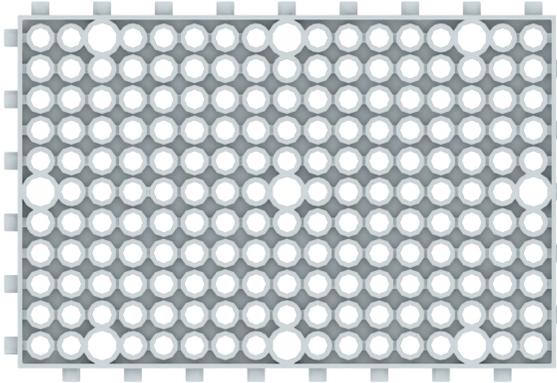
Bloque N 3x5 (1)



Bloque N 3x7 (1)



Bloque 3x5 (4)



Bloque 11x17 (1)



Bloque 1x11 (1)



Remache doble (2)



Adaptador L 3x4 (2)



Rueda polea (1)



Rueda M (2)



Motor 2 (2)



Sensor de infrarrojos (2)



M-shaft

Eje M (1)



Pegatina (1)



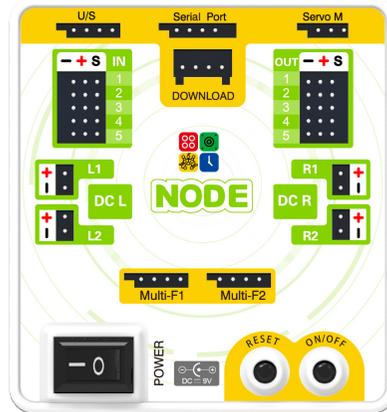
Cable de conexión (3)



Portapilas o portabaterías 1 (1)



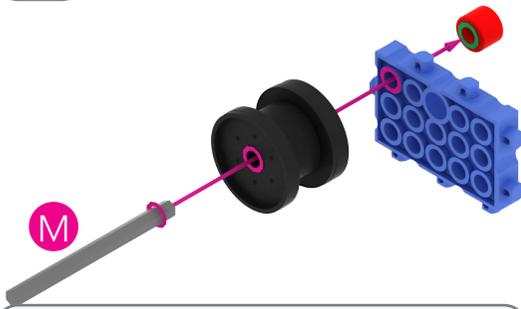
Portapilas o portabaterías 2 (2)



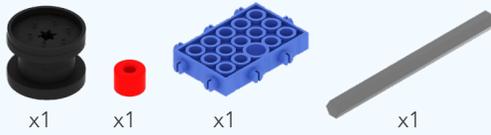
Placa base NODE (1)

01

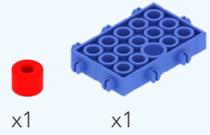
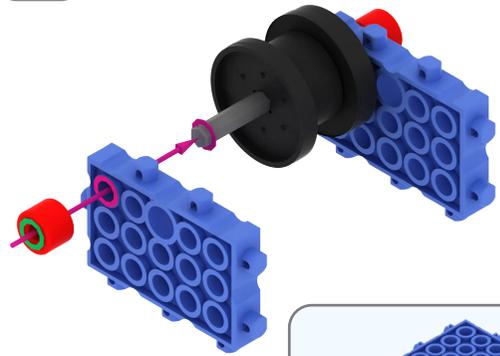
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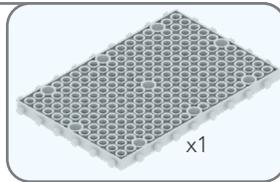
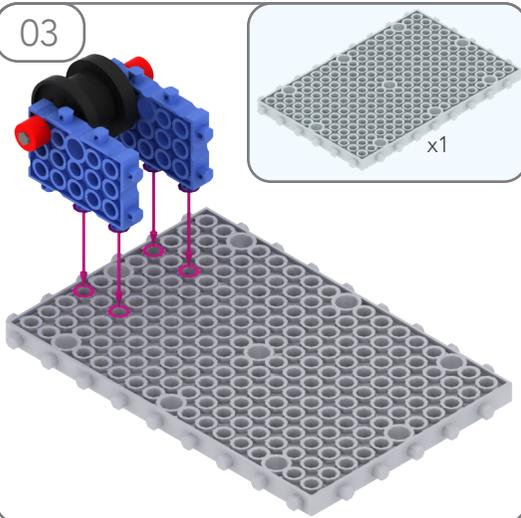
M



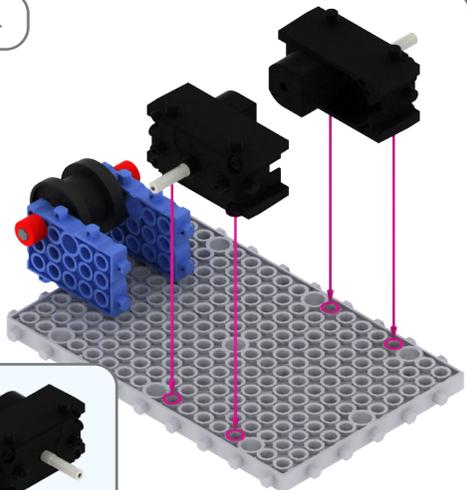
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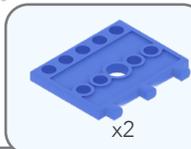
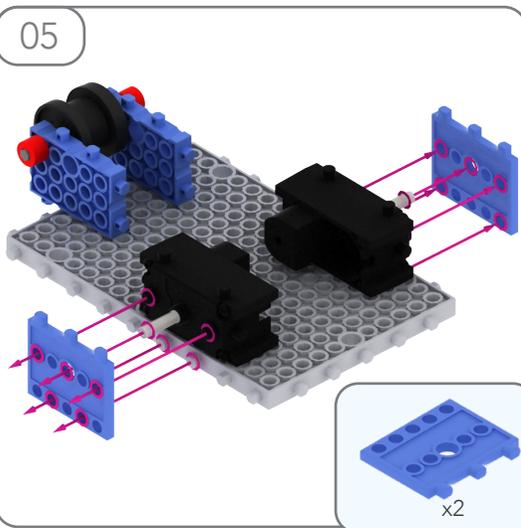
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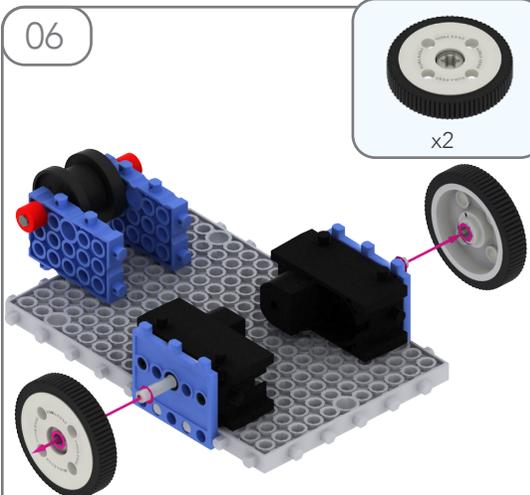
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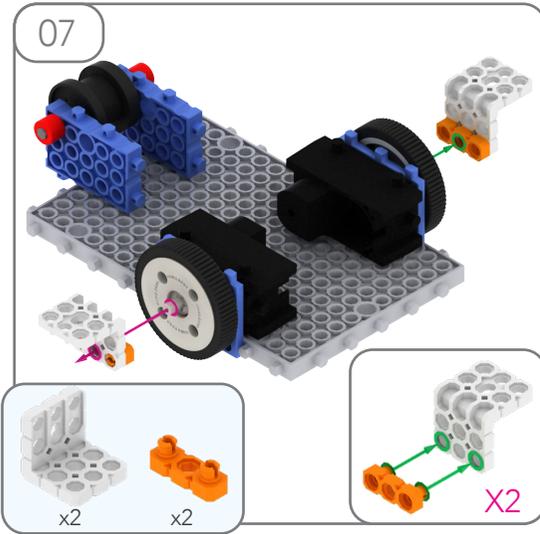
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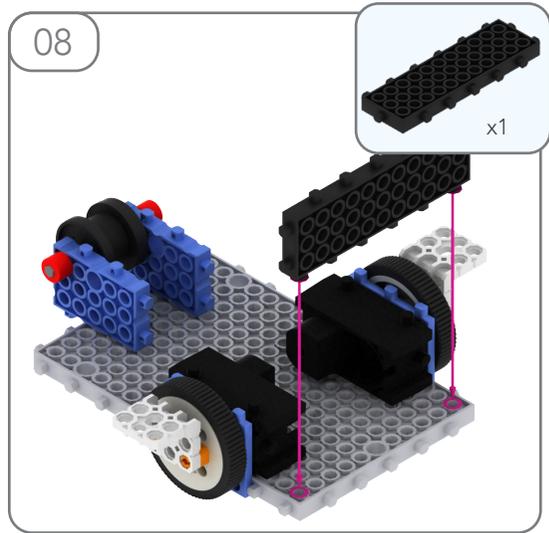
06



07

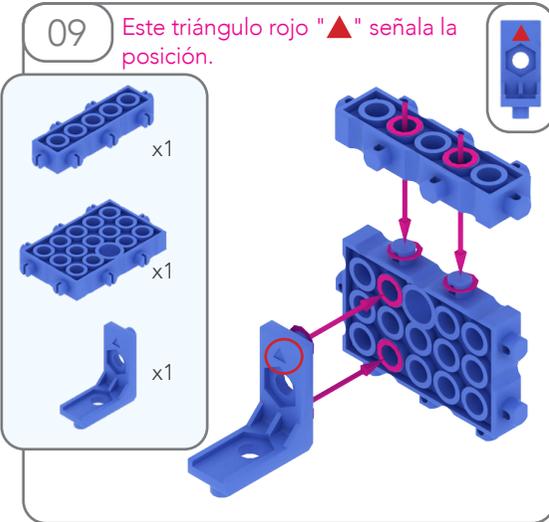


08

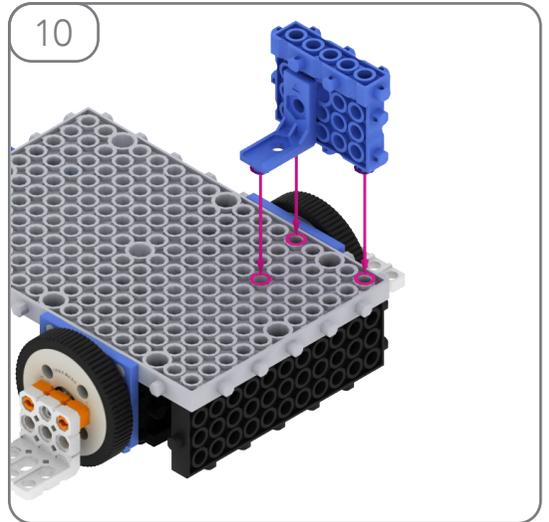


09

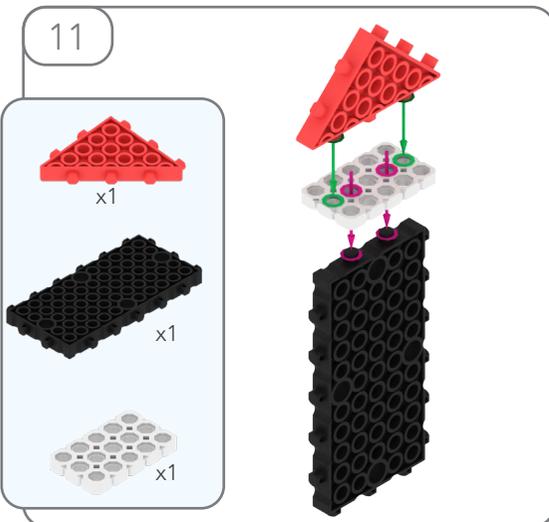
Este triángulo rojo "▲" señala la posición.



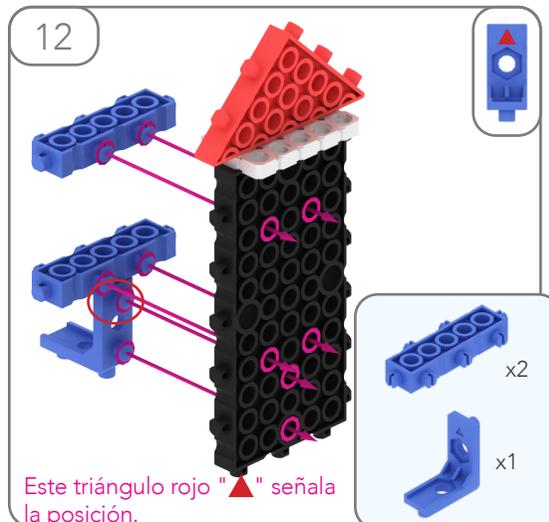
10



11

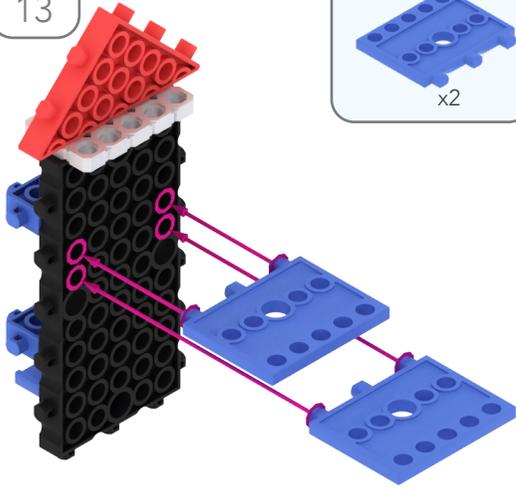


12

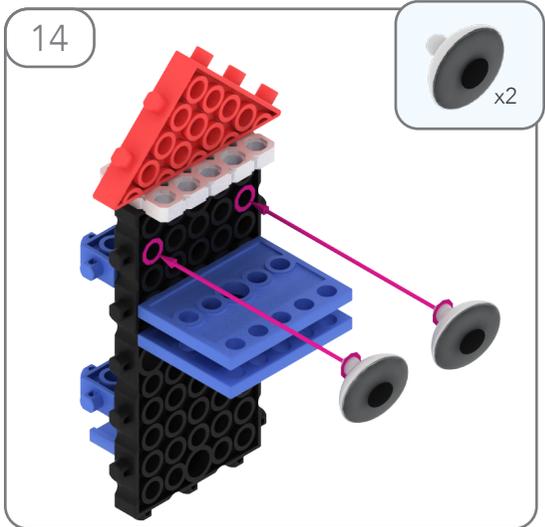


Este triángulo rojo "▲" señala la posición.

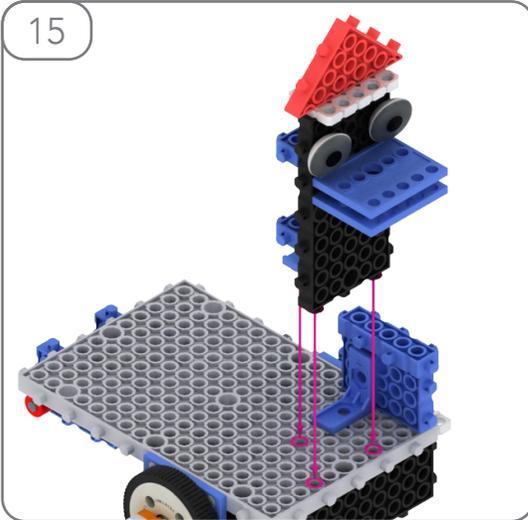
13



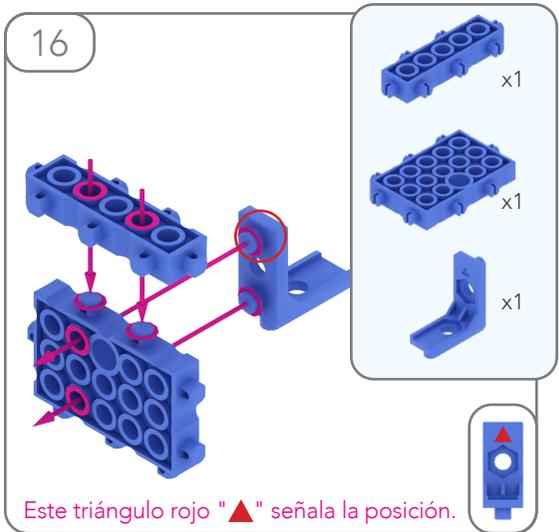
14



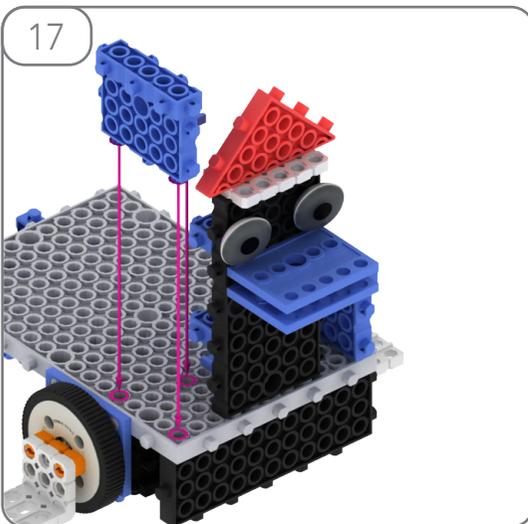
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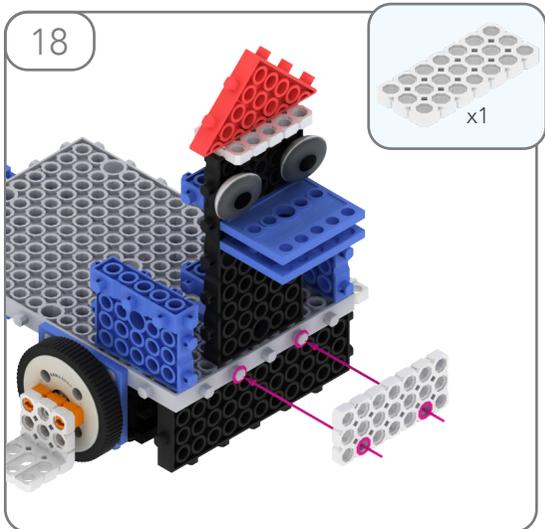
16



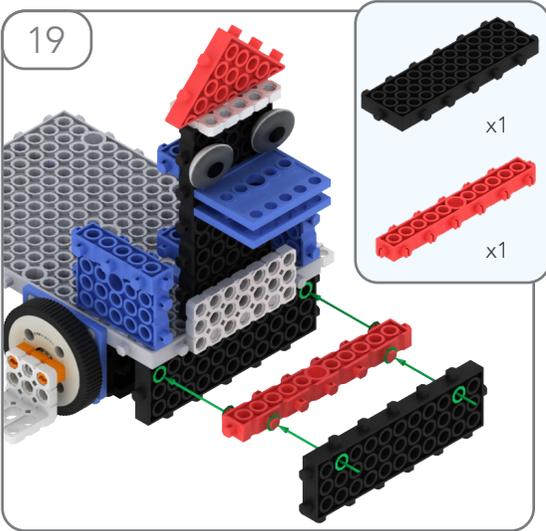
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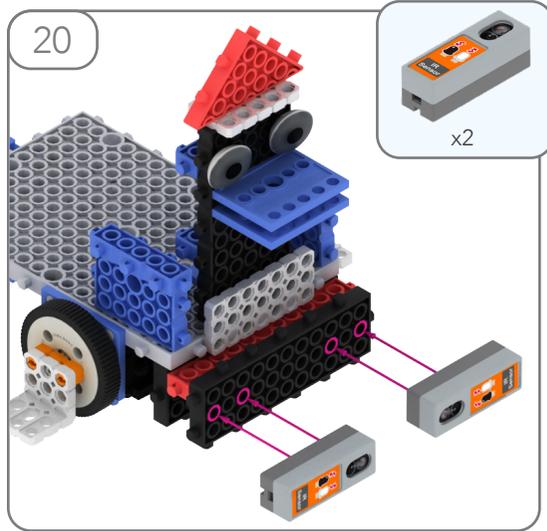
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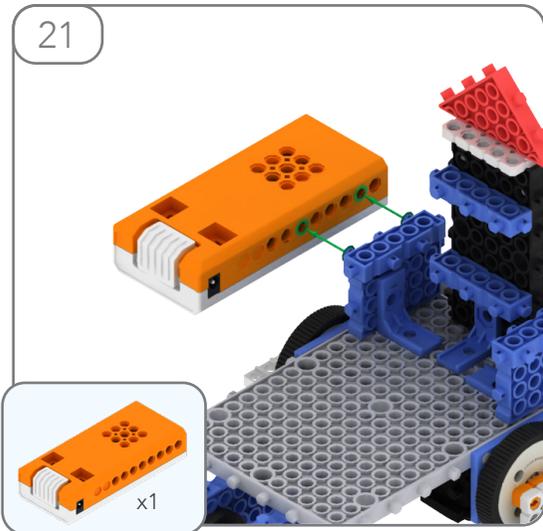
19



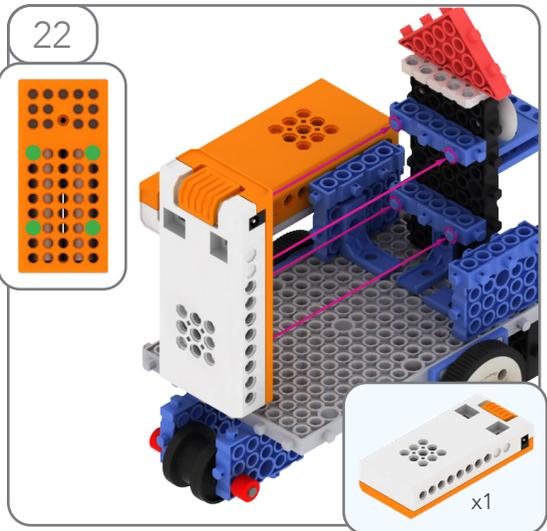
20



21



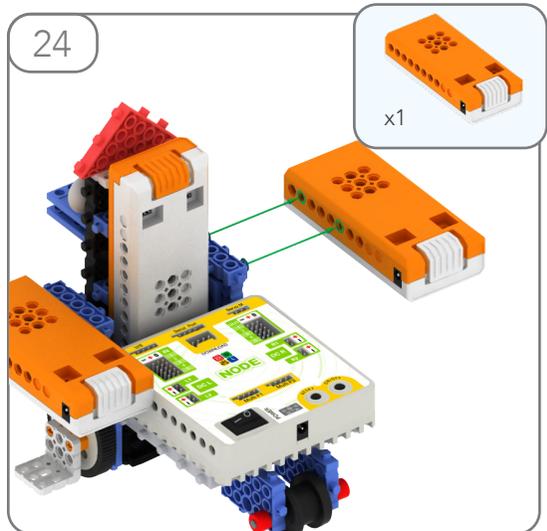
22



23

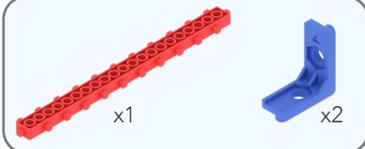
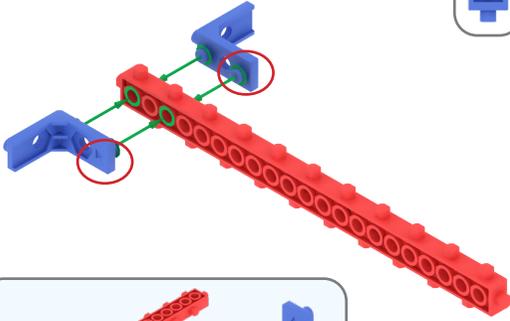


24

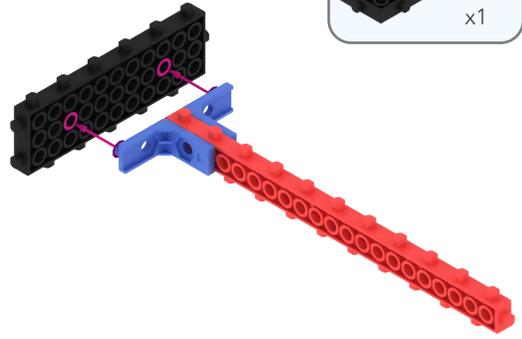
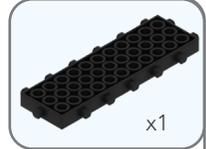


25

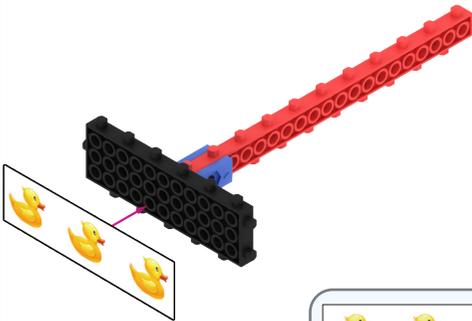
Este triángulo rojo "▲"
señala la posición.



26



27



OK

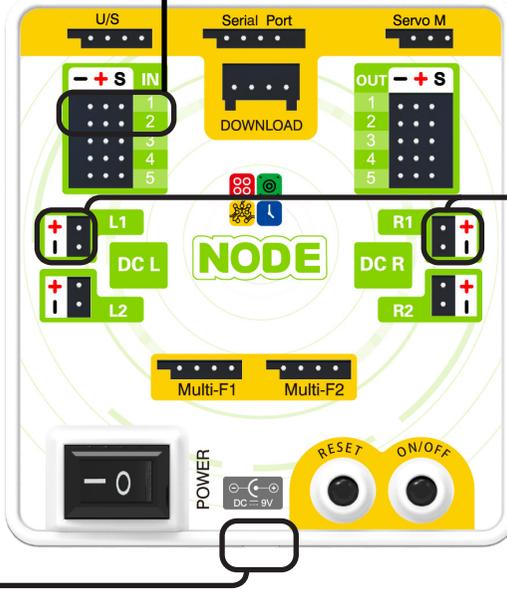
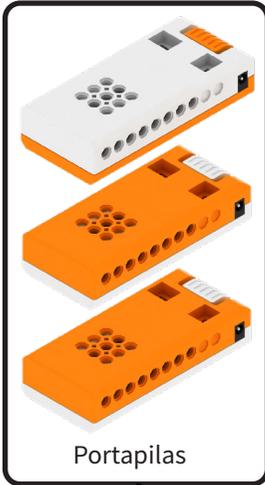


¿Cómo hacer la conexión?

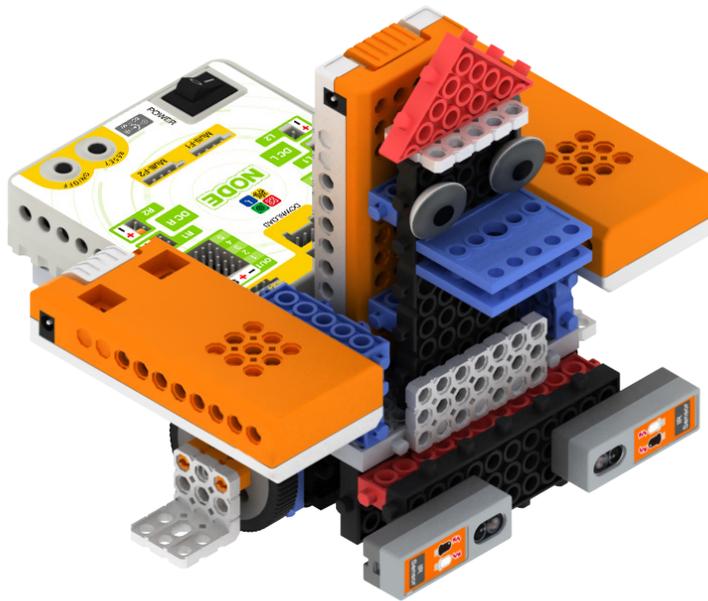
IN1,IN2



POWER

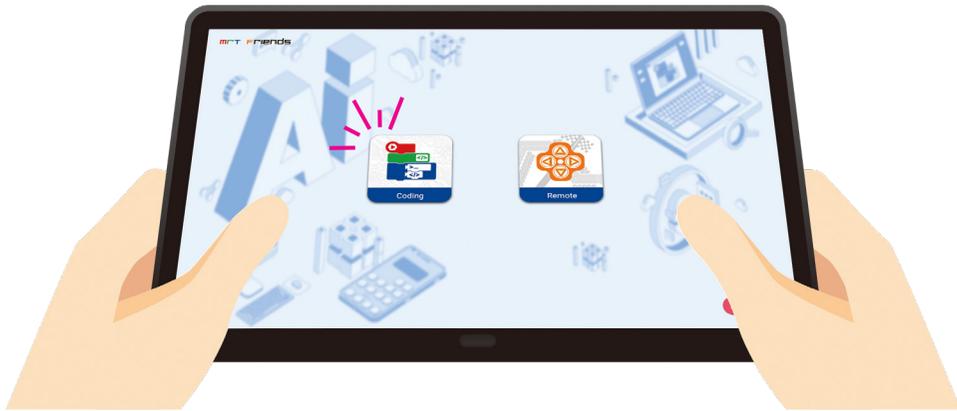


LEFT1,RIGHT1



Practica

1. Haz click en el botón "Coding", situado a la izquierda, para entrar en la interfaz de programación.



2. Haz click en el botón "Samples" para ver algunas configuraciones de ejemplo.



3. Haz click en "Duck".

